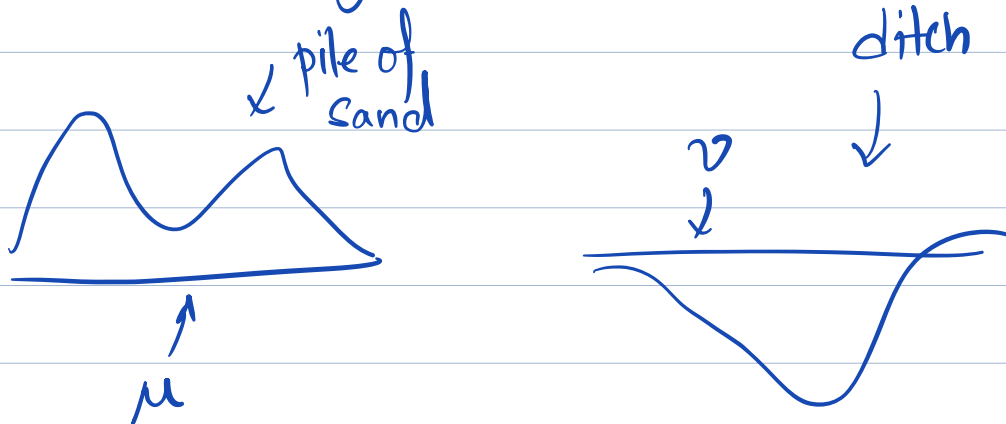


- Introduction
- Organization of lectures

Lecture 1:

- Formulations of OT problem
- Wasserstein distances
- Connecting formulations (Brenier's theorem)
- Duality

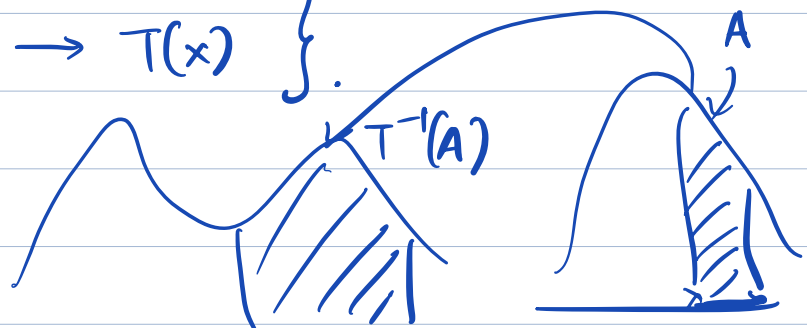
1781 - Monge's formulation



Transporting: $T: \mathbb{R}^d \rightarrow \mathbb{R}^d$

$$x \rightarrow T(x) \}$$

Valid map:



$$\rightarrow \underline{\mu(T^{-1}(A)) = \nu(A)} \quad \text{for every set } A$$

$$X \sim \mu$$

$$T(x) \sim \nu.$$

$$\rightarrow c(x, T(x)) = \|x - T(x)\|$$

Monge's formulation:

Find T :

$$\inf_{\substack{T: \text{valid} \\ \boxed{T_{\#} \mu = \nu}}} \int \|x - T(x)\| d\mu$$

★

1. Are there always maps?
2. What can I say about the OT map?
(stable, regular, unique?)

constraint: $\{T_{\#} \mu = \nu\}$

non-linear, non-convex constraint

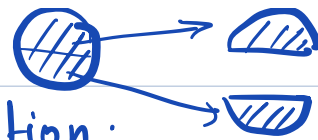
for all x : $\{ \mu(x) = \nu(T(x)) \det(\nabla T(x)) \}$

not always a solution:

$\uparrow$
0
 μ

$\uparrow$
 $-\frac{1}{2}$

$\uparrow$
 $\frac{1}{2}$



ν

No valid map. We need to
split atoms.

Kantorovich (1941)

Define a coupling of μ & ν

$\gamma \rightarrow$ joint distribution

$\rightarrow$ first marginal is μ

$\rightarrow$ second marginal is ν .

$$\gamma(A \times \mathbb{R}^d) = \mu(A) \quad \forall A$$

$$\gamma(\mathbb{R}^d \times A) = \nu(A) \quad \forall A$$

Denote set of all couplings as Γ

Kantorovich's program:

$$\boxed{\begin{array}{l} \text{Find } \Gamma \text{ which} \\ \inf_{\gamma \in \Gamma_{\mu, \nu}} \int \|x - y\| d\gamma(x, y) \end{array}} \quad \star$$

1. Constraint set is nice

infinite-dimensional linear program

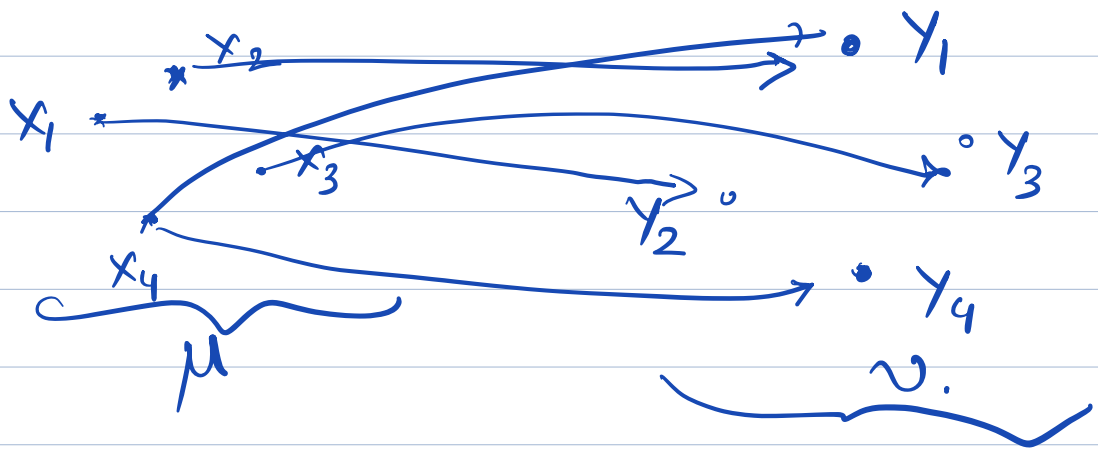
$$\int_{\mathbb{R}^d} \gamma(x, y) dy = \mu(x) \quad \checkmark$$

$$\int_{\mathbb{R}^d} \gamma(x, y) dx = \nu(y).$$

2. There are always valid couplings
 $\begin{array}{l} x \sim \mu \\ y \sim \nu \end{array} \quad \left. \vphantom{\begin{array}{l} x \sim \mu \\ y \sim \nu \end{array}} \right] \text{ "independence coupling"}$

Discrete case:

$$\mu = \frac{1}{n} \sum_{i=1}^n \delta_{x_i} \quad \nu = \frac{1}{n} \sum_{j=1}^n \delta_{y_j}$$



$\gamma \rightarrow$ matrix $(n \times n)$

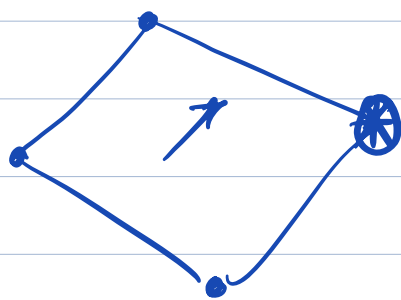
constraints: $\gamma_{ij} \geq 0$

marginal $\rightarrow$ constraints $\sum_j \gamma_{ij} = \frac{1}{n} \quad \forall i$ $\sum_i \gamma_{ij} = \frac{1}{n} \quad \forall j$

objective: $C(x, y) = \|x - y\|$

min $\sum_{i,j} \gamma_{ij} C(x_i, y_j)$
s.t. $\gamma \in \Gamma$

Birkhoff polytope: convex hull of set of permutation matrices.



Monge's problem
also has a
solution in
discrete case.

Wasserstein distances:

Kantorovich's program with ℓ_p cost

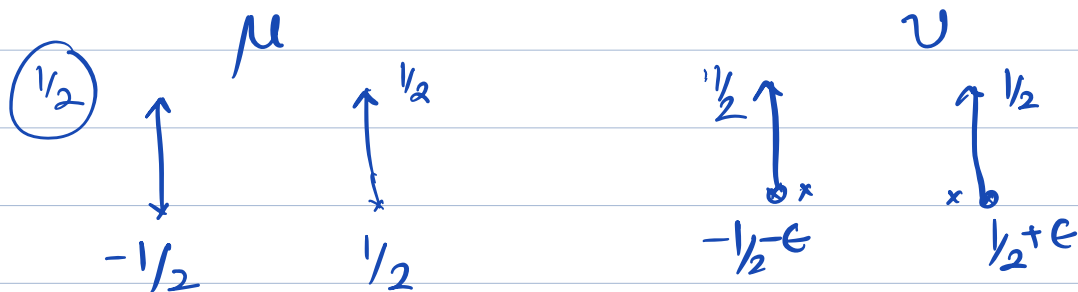
$$C(x, y) = \|x - y\|^p$$

$$\mu, \nu, \quad \int \|x\|^p d\mu < \infty, \quad \int \|y\|^p d\nu < \infty$$

$$W_p^p(\mu, \nu) = \left[\inf_{\gamma \in \Gamma_{\mu, \nu}} \int \|x - y\|^p d\gamma \right]^{1/p}$$

Wasserstein - cost of the best coupling.

1. Metric on distributions,
2. Respects underlying metric structure



Total variation / KL / χ^2 / Hellinger.

↓

1.

↓

∞

$$W_2^2(\mu, \nu) \leq \epsilon^2.$$

Monge & Kantorovich

$p=2$, cost is squared Euclidean

Brenier's theorem: $\rightarrow \mu, \nu \rightarrow$ finite 2nd moments

& μ has a density wrt Lebesgue measure

1. $\exists$ map T_0 , $\boxed{T_{0\#}\mu = \nu}$

T_0 is optimal for Monge's program.

$\rightarrow T_0 = \nabla \varphi_0$ φ_0 is a convex function.

$\nabla \varphi_0$ is unique, μ almost everywhere.

2. γ_0 which solves Kantorovich's problem.

$$\gamma_0 = \underbrace{(x, \nabla \varphi_0(x))}.$$

3. If ν also has a density

$$S_0 \# \nu = \mu$$

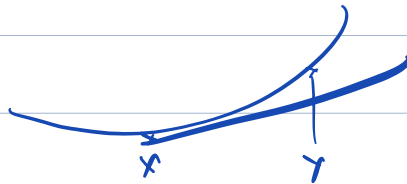
$$S_0 = \nabla \varphi_0^*$$

$$\varphi_0^*(y) = \sup_x [\langle x, y \rangle - \varphi_0(x)].$$

Why is $T_0 = \nabla \varphi_0$?

Gradient of a convex $\simeq$ "multivariate
function monotone".

1D:



$$\rightarrow \left. \begin{array}{l} \varphi(y) \geq \varphi(x) + \nabla \varphi(x)^T (y-x) \\ \varphi(x) \geq \varphi(y) + \nabla \varphi(y)^T (x-y) \end{array} \right\}$$

$$\rightarrow (\nabla \varphi(x) - \nabla \varphi(y))(x - y) \geq 0.$$

$\rightarrow$ if $x \geq y$ then $\nabla \varphi(x) \geq \nabla \varphi(y)$
(ie) $\nabla \varphi$ is monotonic.

Cyclical monotonicity:

$$x_1 \rightarrow x_2 \rightarrow x_3 \rightarrow \dots \rightarrow x_k$$

$$\sum_{i=1}^k (x_i - x_{i+1})^T \nabla \varphi(x_i) \geq 0$$

Duality: (Kantorovich)

Discrete: $\min \sum_{ij} \tau_{ij} c_{ij}$

$$\alpha_j \rightarrow \sum_i \tau_{ij} = 1/n \quad \forall j$$

$$\beta_i \rightarrow \sum_j \tau_{ij} = 1/n \quad \forall i$$

$$\tau_{ij} \rightarrow \tau_{ij} \geq 0. \quad \forall (i,j)$$

$$\min_{\substack{\alpha, \beta, \\ \delta \geq 0}} \max_{\tau_{ij}} \sum_{ij} \tau_{ij} c_{ij} - \sum_j \alpha_j \left(\sum_i \tau_{ij} - \frac{1}{n} \right) - \sum_i \beta_i \left(\sum_j \tau_{ij} - \frac{1}{n} \right) - \sum_{ii} \delta_{ii} \tau_{ii}$$

constraints:

$$C_{ij} - \alpha_j - \beta_i - \delta_{ij} = 0$$

objective: $\max_{\alpha, \beta} \sum_j \alpha_j + \sum_i \beta_i$

$\left[\underbrace{\alpha_j + \beta_i}_{\leq C_{ij}} \right] \leftarrow$

"Shipper's problem".

$\underline{\alpha_j}$ to unload $\underline{Y_j}$
 $\underline{\beta_i}$ to load $\underline{X_i}$

→ Shipper will solve dual.

Strong duality → clever shipper
can set α, β
so that I pay full cost.