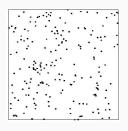
# **Strongly correlated particle systems:**

a toolbox for machine intelligence

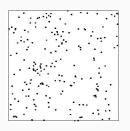
Subhro Ghosh National University of Singapore

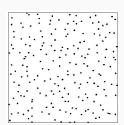
# A gas of particles: ideal vs. real



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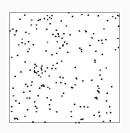
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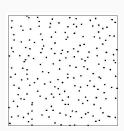
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#### Questions

- Is there a real benefit to exploring beyond IID ?
- Even if there is, would it be realistic?

## Particle systems : ideal vs. real





Ideal

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### **Problem**

IID samples may be less representative or less stable

## Monte Carlo sampling

$$\Lambda(f) := \int f(x) d\mu(x) \longleftrightarrow \Lambda_{\mathcal{S}}(f) := \frac{1}{|\mathcal{S}|} \sum_{i \in \mathcal{S}} f(X_i)$$

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### **Sampling Coresets**

$$L(f) = \sum_{x \in \mathcal{X}} f(x), \quad f \in \mathcal{F} \longleftrightarrow L_{\mathcal{S}}(f) := \sum_{x \in \mathcal{S}} w(x) f(x)$$

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### **Feature Selection**

Sample a subset of columns of a low rank matrix to be representative of the entire matrix

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### **Neural Network Pruning**

Delete redundant edges from a neural network without compromising on quality of output

.....

• "Negative Dependence as a toolbox for machine learning : review and new developments"

H.S. Tran, V. Petrovich, R. Bardenet, S.Ghosh *Arxiv preprint* 

## **IID** samples

Approximation guarantee  $O(m^{-1/2})$ 

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### **Strongly Correlated samples**

Approximation guarantee  $\mathit{O}(\mathit{m}^{-\gamma}), \gamma > 1/2$ 

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#### **Key benefits**

Significant benefit in settings where function evaluation is costly

- Stochastic Gradient Descent (SGD) for highly complex functions
  - Large scale neural networks
  - Large scale conditional random field (CRF) models

#### **Determinantal Point Processes**

A significant class of natural strongly correlated particle systems are *Determinantal Point Processes* or DPPs :

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A significant class of natural strongly correlated particle systems are *Determinantal Point Processes* or DPPs: combination of tractability and feasibility

- A DPP is a random set of points that all interact with each other, and where the interaction is encoded by a kernel.
- DPPs are, in a sense, the kernel machine of particle systems.

### Origins in physics

DPPs originate canonically in quantum and statistical physics

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- DPP strtucture arises as Slater determinants in wave-functions for Fermions (following earlier work by Heisenberg and Dirac)
- Connections to a wide interface of physics and mathematics, including random matrices, random polynomials, random networks, Coulomb gases ...

#### **Correlation functions**

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• If  $\alpha_1, \ldots, \alpha_m$  are m fixed locations, then the m-point correlation function  $\rho_m(\alpha_1, \ldots, \alpha_m)$  is the joint probability (density) of having points at the locations  $\alpha_1, \ldots \alpha_m$  in a realization of the random point set.

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- E.g.: for iid points with density  $\rho$  then  $\rho_m(\alpha_1,\ldots,\alpha_m)=\rho^m$

#### Correlation functions of a DPP

The m-point correlation functions of a DPP are given by determinants of a kernel K:

$$\rho_{m}(\alpha_{1},\ldots,\alpha_{m}) = \operatorname{Det} \left[ \begin{array}{cccc} K(\alpha_{1},\alpha_{1}), & \ldots & K(\alpha_{1},\alpha_{m}) \\ \ldots & \ldots & \ldots \\ K(\alpha_{m},\alpha_{1}), & \ldots & K(\alpha_{m},\alpha_{m}) \end{array} \right]$$

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#### **DPP** models

#### Sampling diversity

DPPs are, therefore, effective in modelling situations where the sample points are desired to be very different from each other.

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  - Population is represented by points in some (high dimensional) feature space
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- Applications include Feature Selection, Monte Carlo integration, Coreset selection, Dimensionality Reduction ....

#### **Orthogonal Polynomials**

• For a probability distribution  $\gamma$  on a euclidean space  $\mathbb{R}^d$ , consider the monomial functions  $(x_1, \ldots, x_d) \mapsto x_1^{\alpha_1} \cdots x_d^{\alpha_d}$  in the graded lexical order.

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- Then apply the Gram-Schmidt algorithm in  $L^2(\gamma)$  to these ordered monomials.
- This yields a sequence of orthonormal polynomial functions  $(\varphi_k)_{k \in \mathbb{N}}$ , the multivariate orthonormal polynomials w.r.t.  $\gamma$ .
- Construct a DPP with the kernel given by the projection

$$K(x,y) = \sum_{k=0}^{m-1} \varphi_k(x)\varphi_k(y),$$

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An effective choice of kernel for sampling applications: Projection kernel onto spaces of orthogonal polynomials (OP)  $\subseteq L^2(\mu)$ 

- Computing OP kernels equivalent to computing moments of  $\mu$
- Rank of kernel = number of moments needed = sample size
- Can be naturally extended to Reproducing Kernel Hilbert Space (RKHS) of approximating functions

# Theorem (Bardenet-G.-Simon-Tran'24 ; Bardenet-G.-Lin'21)

• OP based DPP samplers give approximation guarantees  $O_P\left(m^{-(1/2+1/(2d))}\right)$ 

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- Here d may be taken to be the reduced dimension of the data (after pre-processing via dimension reduction)
- DPP is fundamentally a Hilbert space based technique, so it works well with linear projection based dimension reduction methods

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#### Regularity and rates

- Better rates possible for function classes with smoothness properties using RKHS techniques
- Interplay between smoothness of objective and rate of DPP approximation remains to be fully understood

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$$\mathbb{P}(\|\Lambda_m(\Phi) - \mathbb{E}[\Lambda_m(\Phi)]\| \ge \varepsilon) \le 2m \exp\Big(-\frac{\varepsilon^2}{4A\|\mathbb{V}(\Phi)\|^2}\Big),$$

for 
$$0 \le \varepsilon \le \frac{2A\|\mathbb{V}(\Phi)\|}{3} \cdot \min_{1 \le i \le m} \frac{\sqrt{\operatorname{Var} \Lambda_m(\varphi_i)}}{\|\varphi_i\|_{\infty}} \cdot$$

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#### Concentration and strong dependence

- This is an example of a concentration phenomenon (with features similar to those for independent r.v.s), but in the context of strongly dependent stochastic model.
- Underscores how DPP blends strong dependence with structure and tractability, which allows for such powerful results

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- DPP samplers provide a notion of a "stochastic grid pattern" when there may not even be any geometry to support the notion of a grid
- The power of abstraction: DPPs are able to handle abstract spaces without geometry by looking at the function space on top of that space, thereby bringing to bear many tools from Euclidean spaces

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- If not, we are reduced to importance sampling, which achieves improvement only in the leading constant
- It is crucial that the kernel K is a projection operator on  $L^2(\mu)$ , otherwise fluctuations are Poissonian in nature, and usually of similar order as independent sampling

#### **Sampling from DPPs**

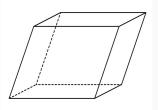
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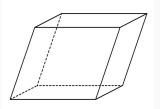
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## Gillenwater et al '19 ; Tremblay et al '23 ; Anari et al '24

New tree-based algorithms built on top of the classical spectral sampler gives fast computational load of  $O(m^2 \log N)$  (and similar) for each sample

## **Statistical Learning Theory**

#### Key challenges

- Lack of independence of sample points renders fundamental empirical process techniques ineffective
- Eg, the basic symmetrization trick fails!
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## Theorem (Dong-G.-Mendelson-Tran, preliminary results) In 1D, we have

$$\mathbb{E}\left[\sup_{f\in\mathcal{H}^2(\mathbb{T})}|\Lambda_m(f)-\mathbb{E}\left[\Lambda_m(f)\right]|\right]\lesssim \frac{\sqrt{\log m}}{m}$$

- Better than Gaussian rates (compared to independent samples)
- Compare: Discrepancy lower bound is O(1/m)

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- The GDP is indexed by the space of positive definite matrices of a given dimension, which we will call the scattering matrix
- Connection to Spiked Models of random matrices and Spiked PCA
- Applications to dimension reduction and clustering
- New kinds of random matrix phenomena based on truncated covariance matrices, leading to novel spectral asymptotics and connections with free probability ...

#### **Gaussian Determinantal Processes**

- A DPP is specified by the underlying kernel.
- The points of a GDP lives on  $\mathbb{R}^d$ , and the kernel is simply the d-dimensional Gaussian density with some positive definite covariance matrix  $\Sigma$  (which is the scattering matrix parameterizing the GDP):

$$K(x,y) = \frac{1}{(2\pi)^{d/2}\sqrt{\mathrm{Det}(\Sigma)}} \exp\left(-\frac{1}{2}(x-y)^T \Sigma^{-1}(x-y)\right).$$

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- Our observation consists of the points in a realisation of the GDP inside a ball of large radius R.

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- Note that modulating  $\Sigma$  such that  $\mathrm{Det}(\Sigma)$  changes will lead to a change in the mean density of points, and can be detected simply by estimating this average density from the observed points.
- We will therefore focus on parametric modulation that leaves the determinant  $\mathrm{Det}(\Sigma)$  invariant similar to shear mappings or shear transformations.

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•  $\lambda=0$  makes  $\Sigma=I_d$  - the 'isotropic' model with no directional bias in the dependency structure of the points.

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- Formally, for a unit vector u and  $\lambda > 0$ , we will consider

$$\Sigma = (1 + \lambda)uu^{T} + (1 + \lambda)^{-\frac{1}{d-1}}(I_{d} - uu^{T}).$$

- $\lambda=0$  makes  $\Sigma=I_d$  the 'isotropic' model with no directional bias in the dependency structure of the points.
- $\lambda>0$  corresponds to a spiked model that introduces directional bias in the strength of the dependency structure.

• The dependence (in this case, repulsion) between the points is much stronger, e.g. much more long-ranged (on the scale  $1+\lambda$ ), in the spike direction u.

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- The dependence in the directions orthogonal to the spike is much weaker, and decouples to almost independent behaviour at relatively short length scales.

#### Parameter estimation in GDP

$$\hat{\Sigma} = |B(1)| \frac{r^{d+2}}{d+2} I_d - \frac{1}{|B(R-r)|} \sum_{\|X_i - X_j\| < r} (X_i - X_j) (X_i - X_j)^T$$

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is a consistent estimator of  $\Sigma$ .

- Bias variance tradeoff leads to optimal choice of  $r = \Theta(\sqrt{d \log n})$ .
- Test statistics  $\lambda_{\max}(\hat{\Sigma})$ ,  $u_{\max}(\hat{\Sigma})$  allow detection of anisotropic direction with high probability if the spike size  $\lambda$  is above a threshold  $\lambda_{n,d}$  (connections to BBP phase transition in spiked models of random matrices)
- Leads to study of truncated, and more generally, kernelized covariance matrices

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- Roughly speaking, dimension reduction involves finding a low-dimensional subspace, or equivalently, a small number of 'significant directions', which contains most of the information about the (high dimensional) data.

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- In P.C.A., we are interested in the directions of maximal variability, which are obtained by taking the principal eigen-directions of the empirical covariance matrix of the data.
- We may view the problem more generally, where dimension reduction will be performed by finding the optimal directions with respect to some other feature (as opposed to variance in the case of P.C.A.)

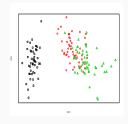
#### **Dimension Reduction**

 We use the GDP model as an ansatz for proposing a dimension reduction methodology.

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- We use the GDP model as an ansatz for proposing a dimension reduction methodology.
- We may compute the quantity  $\hat{\Sigma}$  for any observed data set in  $\mathbb{R}^d$ . We then perform SVD on  $\hat{\Sigma}$  and project the data points on to the principal eigen-directions of  $\hat{\Sigma}$  in order to uncover low dimensional directional features in the data.

#### **Dimension Reduction: Fisher's Iris**

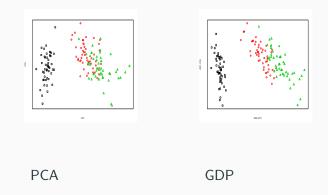


PCA

# Dimension Reduction : Fisher's Iris



#### **Dimension Reduction: Fisher's Iris**



## Theoretical analysis

In progress (with Dong, Mukherjee and Talukdar): minimax optimal guarantees for GDP-based clustering algorithms.

## Kernelized sample covariance matrices

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$$M_{\beta,n} = \frac{1}{2n^2} \sum_{1 \le i,j \le n} K_{\beta}(X_i, X_j) (X_i - X_j) (X_i - X_j)^{\top}$$

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Typically:

$$K_{\beta}(x, y) = \varphi_{\beta}(D(x, y)),$$

where D is a distance and  $\beta$  can scale with dimension.

- The indicator kernel  $\mathbb{I}(\|x-y\| \le r_{n,d})$
- The Gaussian kernel  $1 \exp \left( \frac{\|x y\|^2}{2\tau_{n,d}^2} \right)$

# Limiting Spectral Laws of kernelized covariance matrices (with Mukherjee and Talukdar, arxiv)

• Depending on regularity properties of the kernel  $K_{\beta}$ , different asymptotic spectral laws can be established when the  $X_i$ 's are i.i.d.

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- For smooth kernels, shifted and scaled family of Marcenko-Pastur type laws
- For non-smooth kernels, provable convergence to a more complicated spectral asymptotics that is characterised implicitly by an equation on the Stieltjes transform
- Crucial issue is the dependence between the coefficient  $K_{\beta}(X_1, X_j)$  and the rank 1 matrix  $(X_i X_j)(X_i X_j)^{\top}$ .

## Zeros of Gaussian power series

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$$\sum_{k=0}^{\infty} \xi_k \frac{z^k}{\sqrt{k!}}$$

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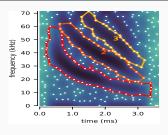
#### Zeros of Gaussian power series

A different strongly correlated random point field: zeros of Gaussian power series

$$\sum_{k=0}^{\infty} \xi_k \frac{z^k}{\sqrt{k!}}$$

- Arises in the study of quantum chaotic eigenstates (Bogomolny, Bohigas, Lebeouf, Nonenmacher, Voros ...)
- Captures the distribution of zeros of short time Fourier transform (STFT) of white noise

# Gaussian zeros and signal processing



Bat echolocation signal

#### Gaussian zeros and signal processing

- Gaussian zeros form a strongly correlated point set
- Strongly rigid geometry makes deviations easy to detect
- Amenable to topological data analysis tools for signal reconstruction in a wide class of time indexed problems (incl. gravitational waves)

$$\operatorname{Var}\left[\Lambda_{m}(f)\right] = \iint \|f(\mathbf{z}) - f(\mathbf{w})\|_{2}^{2} |K_{m}(\mathbf{z}, \mathbf{w})|^{2} d\mu(\mathbf{z}) d\mu(\mathbf{w})$$

$$\lesssim \mathcal{M}(f) \cdot \frac{1}{m^{2}} \int \int \|\mathbf{z} - \mathbf{w}\|_{2}^{2} |K_{m}(\mathbf{z}, \mathbf{w})|^{2} d\mu(\mathbf{z}) d\mu(\mathbf{w})$$

- If  $||z w||_2^2$  was not present, then  $\iint |K_m(\mathbf{z}, \mathbf{w})|^2 \mathrm{d}\mu(\mathbf{z}) \mathrm{d}\mu(\mathbf{w}) = m \text{ implies } \mathrm{Var} \lesssim m^{-1}, \text{ same as uniform random sampling}$
- Main contribution to  $\iint |K_m(\mathbf{z}, \mathbf{w})|^2 d\mu(\mathbf{z}) d\mu(\mathbf{w})$  comes from near the diagonal  $\mathbf{z} = \mathbf{w}$ , which is precisely suppressed by the term  $\|\mathbf{z} \mathbf{w}\|_2^2$ .
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