Complexity, Holography & Quantum Field Theory

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R. Jefferson & RCM, arXiv:1707.xxxxx

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Holographic Complexity: A Tale of Two Dualities

 <u>complexity=volume</u>: evaluate proper volume of extremal codim-one surface connecting Cauchy surfaces in boundary theory (cf holo EE) (Stanford & Susskind)



- <u>complexity=action</u>: evaluate gravitational action for Wheeler-DeWitt patch = domain of dependence of bulk time slice connecting boundary Cauchy slices in CFT (Brown, Roberts, Swingle, Susskind & Zhao)
- both of these gravitational "observables" probe the black hole interior (at arbitrarily late times on boundary)

Questions?

- What is "holographic complexity"?
 - what is boundary dual of these gravitational observables?
 - > QFT/path integral description of "complexity" in boundary CFT?
- is there a privileged role for (states on) null Cauchy surfaces?
 - provide distinguished reference states?
- is there a "renormalized holographic complexity"?
 - what's it good for?; (EE vs mutual information versions of F)
- ambiguities? ambiguities? ambiguities?
 - connections between ambiguities in gravity and boundary?
- more boundary terms: higher codim. intersections; "complex" joint contributions; boundary "counterterms"
- why is complexity of formation positive?
- C_A contribution of spacetime singularity? subregion complexity?

Questions?

- What is "holographic complexity"?
 - what is boundary dual of these gravitational observables?
 - QFT/path integral description of "complexity" in boundary CFT?
- is there a privileged role for (states on) null Cauchy surfaces?
 - provide distinguished reference states?
- is there a
 > wha
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 What does "complexity" mean in a quantum field theory?
 (Tentative first steps w/ R. Jefferson)
 of F)
- more boundary terms: higher codim. intersections; "complex" joint contributions; boundary "counterterms"
- why is complexity of formation positive?
- \mathcal{C}_A contribution of spacetime singularity? subregion complexity?

Complexity in Quantum Field Theory??

- computational complexity: how difficult is it to implement a task? eg, how difficult is it to prepare a particular state?
- quantum circuit model:





Hadamard gate



Phase-shift gate



Ancillary gate





Complexity in Quantum Field Theory??

 computational complexity: how difficult is it to implement a task? eg, how difficult is it to prepare a particular state?



- complexity = minimum number of gates required to prepare the desired target state (ie, need to find optimal circuit)
- does the answer depend on the choices??

Complexity in Quantum Field Theory??

 computational complexity: how difficult is it to implement a task? eg, how difficult is it to prepare a particular state?



- complexity = minimum number of gates required to prepare the desired target state (ie, need to find optimal circuit)
- does the answer depend on the choices?? YES!!

Quantum Field Theory:

• free scalar field theory (in d spacetime dimensions)

$$H = \frac{1}{2} \int d^{d-1}x \left[\pi(x)^2 + \vec{\nabla}\phi(x)^2 + m^2\phi(x)^2 \right]$$

Quantum Field Theory:

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$$H = \frac{1}{2} \int d^{d-1}x \left[\pi(x)^2 + \vec{\nabla}\phi(x)^2 + m^2\phi(x)^2 \right]$$
$$= \frac{1}{2} \sum_{\vec{n}} \left[\frac{p(\vec{n})^2}{\delta^{d-1}} + \delta^{d-1} \left\{ \frac{1}{\delta^2} \sum_{i} [\phi(\vec{n}) - \phi(\vec{n} - \hat{x}_i)]^2 + m^2\phi(\vec{n})^2 \right\} \right]$$



Quantum Field Theory:

• an infinite family of coupled harmonic oscillators

$$H = \frac{1}{2} \int d^{d-1}x \left[\pi(x)^2 + \vec{\nabla}\phi(x)^2 + m^2\phi(x)^2 \right]$$

$$= \frac{1}{2} \sum_{\vec{n}} \left[\frac{P(\vec{n})^2}{M} + M \left\{ 2 \sum_{i} [X(\vec{n}) - X(\vec{n} - \hat{x}_i)]^2 + \omega^2 X(\vec{n})^2 \right\} \right]$$

$$P(\vec{n}) = \delta^{-d/2} p(\vec{n})$$

$$X(\vec{n}) = \delta^{d/2} \phi(\vec{n})$$

$$M = 1/\delta$$

$$\Omega^2 = 1/\delta^2$$

$$\omega^2 = m^2$$

$$H = \frac{1}{2} \left[p_1^2 + p_2^2 + \omega^2 \left(x_1^2 + x_2^2 \right) + \Omega^2 \left(x_1 - x_2 \right)^2 \right] \qquad (M = 1)$$

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$$= \frac{1}{2} \left[p_+^2 + \omega_+^2 x_+^2 + p_-^2 + \omega_-^2 x_-^2 \right] \text{ with } x_{\pm} = \frac{1}{\sqrt{2}} \left(x_1 \pm x_2 \right) ,$$

$$\omega_+^2 = \omega^2 , \quad \omega_- = \omega^2 + 2\Omega^2$$

find normal modes; problem reduces to two independent SHO's

$$\begin{split} H &= \frac{1}{2} \left[p_1^2 + p_2^2 + \omega^2 \left(x_1^2 + x_2^2 \right) + \Omega^2 \left(x_1 - x_2 \right)^2 \right] & (M = 1) \\ &= \frac{1}{2} \left[p_+^2 + \omega_+^2 x_+^2 + p_-^2 + \omega_-^2 x_-^2 \right] \text{ with } x_{\pm} &= \frac{1}{\sqrt{2}} \left(x_1 \pm x_2 \right) , \\ &\omega_+^2 &= \omega^2 , \quad \omega_-^2 = \omega^2 + 2\Omega^2 \end{split}$$

• ground-state wave-function:

$$\begin{split} \Psi_0(x_+, x_-) &= \Psi_0(x_+) \,\Psi_0(x_-) = \frac{(\omega_+ \omega_-)^{1/4}}{\sqrt{\pi}} \,\exp\left[-\frac{1}{2} \left(\omega_+ x_+^2 + \omega_- x_-^2\right)\right] \\ \Psi_0(x_1, x_2) &= \frac{(\omega_+ \omega_-)^{1/4}}{\sqrt{\pi}} \,\exp\left[-\frac{1}{4} \left(\omega_+ \left(x_1 + x_2\right)^2 + \omega_- \left(x_1 - x_2\right)^2\right)\right] \\ &= \frac{(\omega_1^2 - \beta^2)^{1/4}}{\sqrt{\pi}} \,\exp\left[-\frac{1}{2} \,\omega_1 \,x_1^2 - \frac{1}{2} \,\omega_1 \,x_2^2 - \beta \,x_1 x_2\right] \\ &\text{ with } \quad \omega_1 = \frac{\omega_+ + \omega_-}{2} \quad \text{ and } \quad \beta = \frac{\omega_+ - \omega_-}{2} < 0 \end{split}$$

$$\begin{split} H &= \frac{1}{2} \left[p_1^2 + p_2^2 + \omega^2 \left(x_1^2 + x_2^2 \right) + \Omega^2 \left(x_1 - x_2 \right)^2 \right] & (M = 1) \\ &= \frac{1}{2} \left[p_+^2 + \omega_+^2 x_+^2 + p_-^2 + \omega_-^2 x_-^2 \right] \text{ with } x_{\pm} &= \frac{1}{\sqrt{2}} \left(x_1 \pm x_2 \right) , \\ &\omega_+^2 &= \omega^2 , \quad \omega_-^2 = \omega^2 + 2\Omega^2 \end{split}$$

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Target state:
$$\psi_T(x_1, x_2) \simeq \exp\left[-\frac{1}{2}\omega_1 x_1^2 - \frac{1}{2}\omega_1 x_2^2 - \beta x_1 x_2\right]$$

Reference state: ??????

Target state:
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Reference state: $\psi_R(x_1, x_2) \simeq \exp\left[-\frac{1}{2}\omega_0 x_1^2 - \frac{1}{2}\omega_0 x_2^2\right]$

• factorized Gaussian: $(\omega_0 x_i + i p_i) \psi_R(x_i) = 0$

Target state:
$$\psi_T(x_1, x_2) \simeq \exp\left[-\frac{1}{2}\omega_1 x_1^2 - \frac{1}{2}\omega_1 x_2^2 - \beta x_1 x_2\right]$$

Reference state: $\psi_R(x_1, x_2) \simeq \exp\left[-\frac{1}{2}\omega_0 x_1^2 - \frac{1}{2}\omega_0 x_2^2\right]$

Gates/Unitaries: ?????

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Gates/Unitaries:

• natural operators: x_1, x_2, p_1, p_2 $[x_i, p_j] = i \delta_{ij}$

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Gates/Unitaries:

• natural operators:
$$x_1, x_2, p_1, p_2$$
 $[x_i, p_j] = i \, \delta_{ij}$

$$\begin{array}{c} \longrightarrow \\ Q_{00} = \exp[i\epsilon \, x_0 \, p_0] \\ & \uparrow & \uparrow \\ & \text{infinitesimal} \\ & \text{parameter} \\ & \epsilon \ll 1 \end{array}$$

"add a small phase"

Target state:
$$\psi_T(x_1, x_2) \simeq \exp\left[-\frac{1}{2}\omega_1 x_1^2 - \frac{1}{2}\omega_1 x_2^2 - \beta x_1 x_2\right]$$

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Gates/Unitaries:

• natural operators: x_1 , x_2 , p_1 , p_2 $[x_i, p_j] = i \, \delta_{ij}$ • $Q_{00} = \exp[i\epsilon x_0 p_0]$ "add a small phase" $Q_{0i} = \exp[i\epsilon x_0 p_i]$ "shift x_i by ϵx_0 " $Q_{i0} = \exp[i\epsilon x_i p_0]$ "shift p_i by ϵp_0 " (mulitply by small plane wave component)

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Gates/Unitaries:

• natural operators: x_1, x_2, p_1, p_2 $|x_i, p_j| = i \,\delta_{ij}$ $Q_{00} = \exp[i\epsilon x_0 p_0]$ "add a small phase" $Q_{0i} = \exp[i\epsilon x_0 p_i]$ "shift x_i by ϵx_0 " "shift p_i by ϵp_0 " $Q_{i0} = \exp[i\epsilon x_i p_0]$ (mulitply by small plane wave component) $Q_{ij} = \exp[i\epsilon x_i p_j]$ $(i \neq j)$ "shift x_i by ϵx_i " (entangling) $Q_{ii} = \exp\left[i\frac{\epsilon}{2}(x_i \, p_i + p_i \, x_i)\right]$ "rescale x_i to $e^{\epsilon} x_i$ " (scaling) $=e^{\epsilon/2} \exp[i\epsilon x_i p_i]$





"circuit depth": $\mathcal{D}_1 = |\alpha_1| + |\alpha_2| + |\alpha_3|$ $= \frac{1}{2\epsilon} \log \left[\frac{\omega_1^2 - \beta^2}{\omega_0^2}\right] + \frac{|\beta|}{\epsilon} \sqrt{\frac{\omega_0}{\omega_1}} \left(\omega_1^2 - \beta^2\right)^{-1/2}$



"circuit depth": $\mathcal{D}_1 = |\alpha_1| + |\alpha_2| + |\alpha_3|$ $= \frac{1}{2\epsilon} \log \left[\frac{\omega_1^2 - \beta^2}{\omega_0^2}\right] + \frac{|\beta|}{\epsilon} \sqrt{\frac{\omega_0}{\omega_1}} \left(\omega_1^2 - \beta^2\right)^{-1/2}$

How do we find optimal circuit??

• follow approach of Mike Neilsen (eg, Hamiltonian control theory) Nielsen [arXiv:0502070]; Neilsen et al [arXiv:0603161]; Neilsen & Dowling [arXiv:0701004]

Nielsen approach:

• work with smooth functions on a smooth space (rather than discrete)

$$\psi_T(x_1, x_2) = U \psi_R(x_1, x_2)$$
 with $U = \mathcal{P} \exp\left[\int_0^1 ds \ Y^I(s) \mathcal{O}_I\right]$

where
$$\mathcal{O}_{11} = \frac{i}{2} (x_1 p_1 + p_1 x_1), \quad \mathcal{O}_{12} = i x_1 p_2,$$

 $\mathcal{O}_{22} = \frac{i}{2} (x_2 p_2 + p_2 x_2), \quad \mathcal{O}_{21} = i x_2 p_1$

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right-to-left s : position label
where $\mathcal{O}_{11} = \frac{i}{2} \left(x_1 \ p_1 + p_1 \ x_1 \right), \quad \mathcal{O}_{12} = i \ x_1 \ p_2,$
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Nielsen approach:

• work with smooth functions on a smooth space (rather than discrete)

$$\Delta s = \epsilon \quad \text{on/off}$$

$$\psi_T(x_1, x_2) = U \psi_R(x_1, x_2) \quad \text{with} \quad U = \Pr\left[\int_0^1 ds \ Y^I(s) \ \mathcal{O}_I\right]$$
right-to-left $s: \text{position label}$
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• consider trajectories:

$$U(s) = \mathcal{P} \exp \left[\int_0^s d\tilde{s} \ Y^I(\tilde{s}) \ M_I \right] \quad \text{where} \quad U(s=0) = 1 \,, \quad U(s=1) = U_{fin}$$

$$\mathsf{velocity:} \ Y^I(s) = \mathrm{Tr} \left[\partial_s U(s) \ U^{-1}(s) \ M_I \right]$$

Nielsen approach:

- work with smooth functions on a smooth space (rather than discrete)
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analogy with motion of a particle determined by minimizing an action

minimizing the cost function/action: $\mathcal{D} = \int_0^1 ds \sum_I |Y^I(s)|$

• extremal path U(s) is geodesic in a Finsler geometry

Nielsen approach:

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analogy with motion of a particle determined by minimizing an action

minimizing the cost function/action: $\mathcal{D} = \int_0^1 ds \sqrt{\sum_{IJ} \delta_{IJ} Y^I(s) Y^J(s)} [F_1 \to F_2]$

extremal path U(s) is geodesic in a Riemannian geometry

Nielsen approach:

- work with smooth functions on a smooth space (rather than discrete)
- consider trajectories:

$$U(s) = \mathcal{P} \exp\left[\int_0^s d\tilde{s} \ Y^I(\tilde{s}) M_I\right] \quad \text{where} \quad U(s=0) = 1 \,, \quad U(s=1) = U_{fin}$$
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analogy with motion of a particle determined by minimizing an action

minimizing the cost function/action: $\mathcal{D} = \int_0^1 ds \sqrt{\sum_{IJ} \frac{g_{IJ} Y^I(s) Y^J(s)}{[F_1 \to F_2 \to F_q]}}$

extremal path U(s) is geodesic in a Riemannian geometry

Nielsen approach: to find optimal circuit

$$\begin{split} \psi_T(x_1, x_2) &= U(s = 1) \, \psi_R(x_1, x_2) \quad \text{with} \quad U(s) = \mathcal{P} \exp\left[\int_0^s d\tilde{s} \ Y^I(\tilde{s}) \, \mathcal{O}_I\right] \\ \text{where} \quad \mathcal{O}_{11} &= \frac{i}{2} \left(x_1 \, p_1 + p_1 \, x_1\right), \quad \mathcal{O}_{12} = i \, x_1 \, p_2, \\ \mathcal{O}_{22} &= \frac{i}{2} \left(x_2 \, p_2 + p_2 \, x_2\right), \quad \mathcal{O}_{21} = i \, x_2 \, p_1 \end{split}$$

• find the "geodesic" minimizing the "action":

$$\mathcal{D} = \int_0^1 ds \left[(Y^{11}(s))^2 + (Y^{22}(s))^2 + (Y^{21}(s))^2 + (Y^{12}(s))^2 \right]^{1/2}$$

• defining $Y^{I}(s) = \operatorname{Tr} \left[\partial_{s} U(s) U^{-1}(s) M_{I} \right]$ with $M_{I} \longrightarrow \mathcal{O}_{I}$?

(But see: Chapman, Heller, Marrochio & Pastawski)

Alternative picture:

• at this stage thinking of Gaussian states, so consider space of states as space of (positive) quadratic forms

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$$\psi \simeq \exp\left[-\frac{1}{2}x_i A_{ij} x_j\right] \longrightarrow A_T = \begin{bmatrix} \omega_1 & \beta \\ \beta & \omega_1 \end{bmatrix}$$
$$A_R = \begin{bmatrix} \omega_0 & 0 \\ 0 & \omega_0 \end{bmatrix}$$

Alternative picture:

• u

• at this stage thinking of Gaussian states, so consider space of states as space of (positive) quadratic forms

$$\psi \simeq \exp\left[-\frac{1}{2}x_{i}A_{ij}x_{j}\right] \longrightarrow A_{T} = \begin{bmatrix} \omega_{1} & \beta \\ \beta & \omega_{1} \end{bmatrix}$$

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$$Q_{ij} = \exp[\epsilon \mathcal{O}_{ij}] \quad \text{with} \quad \mathcal{O}_{ij} = i x_{i} p_{j} + \frac{1}{2} \delta_{ij}$$

$$Q_{ij} = \exp[\epsilon M_{ij}] \quad \text{with} \quad [M_{ij}]_{ab} = \delta_{ia} \delta_{jb}$$

$$eg, \quad M_{11} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

$$where \quad A' = Q_{ij} A \ Q_{ij}^{T}$$

generators of GL(2,R)

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Alternative picture:

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• what would the optimal circuit look like?

$$A_{T} = U(1) A_{R} U^{T}(1) \qquad \text{with} \quad U(s) = \mathcal{P} \exp\left[\int_{0}^{s} d\tilde{s} Y^{I}(\tilde{s}) M_{I}\right]$$
$$A_{R} = \begin{bmatrix} \omega_{0} & 0\\ 0 & \omega_{0} \end{bmatrix} \quad A_{T} = \begin{bmatrix} \omega_{1} & \beta\\ \beta & \omega_{2} \end{bmatrix} \qquad \text{where} \quad [M_{ij}]_{ab} = \delta_{ia} \, \delta_{jb}$$
$$\text{generators of GL(2,R)}$$

• we want to minimize:
$$\mathcal{D} = \int_0^1 ds \; \sum_{ij} \left[(Y^{ij}(s))^2 \right]^{1/2}$$

• defining $Y^{I}(s) = \text{Tr} \left[\partial_{s} U(s) U^{-1}(s) M_{I} \right]$ is now straightforward

finding geodesics for some right invariant metric on GL(2,R) $ds^{2} = \delta_{IJ} \operatorname{Tr} \left[dU(s) U^{-1}(s) M_{I} \right] \operatorname{Tr} \left[dU(s) U^{-1}(s) M_{J} \right]$

 $ds^{2} = 2dy^{2} + 2d\rho^{2} + 2\cosh(2\rho)\cosh^{2}\rho \, d\tau^{2} + 2\cosh(2\rho)\sinh^{2}\rho \, d\theta^{2} - 8\sinh^{2}\rho \, \cosh^{2}\rho \, d\theta d\tau$ • circuits: trajectories in GL(2,R)

 $U(s) = e^{y(s)} \begin{bmatrix} \cos \tau(s) \cosh \rho(s) - \sin \theta(s) \sinh \rho(s) & -\sin \tau(s) \cosh \rho(s) + \cos \theta(s) \sinh \rho(s) \\ \sin \tau(s) \cosh \rho(s) + \cos \theta(s) \sinh \rho(s) & \cos \tau(s) \cosh \rho(s) + \sin \theta(s) \sinh \rho(s) \end{bmatrix}$

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• find geodesics connecting U(s=0) = 1 to U(s=1) where

$$A_T = \begin{bmatrix} \omega_1 & -|\beta| \\ -|\beta| & \omega_1 \end{bmatrix} = \omega_0 U(1) U^T(1)$$

 $ds^{2} = 2dy^{2} + 2d\rho^{2} + 2\cosh(2\rho)\cosh^{2}\rho \, d\tau^{2} + 2\cosh(2\rho)\sinh^{2}\rho \, d\theta^{2} - 8\sinh^{2}\rho \, \cosh^{2}\rho \, d\theta d\tau$ • circuits: trajectories in GL(2,R)

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$$A_T = \begin{bmatrix} \omega_1 & -|\beta| \\ -|\beta| & \omega_1 \end{bmatrix} = \omega_0 U(1) U^T(1)$$

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 $\theta_1 - \tau_1$ is not fixed!

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$$y_{1} = \frac{1}{2} \log \frac{\omega_{1}^{2} - \beta^{2}}{\omega_{0}^{2}} = \frac{1}{2} \log \frac{\omega_{+} \omega_{-}}{\omega_{0}^{2}}$$

$$\rho_{1} = \frac{1}{2} \log \frac{\omega_{1} + |\beta|}{\omega_{1} - |\beta|} = \frac{1}{2} \log \frac{\omega_{-}}{\omega_{+}}$$

$$\theta_{1} + \tau_{1} = \pi$$
minimize in family of geodesics
$$\rho_{1} - \tau_{1} \text{ is not fixed!}$$



Normal modes:

• examine normal circuit in normal mode basis

$$\tilde{x} = Rx \quad \longleftrightarrow \quad \begin{bmatrix} x_{-} \\ x_{+} \end{bmatrix} = R \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix} \quad \text{with} \quad R = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$$

$$\longrightarrow \quad \tilde{A}_{T} = RA_{T}R^{\dagger} = \begin{bmatrix} \omega_{-} & 0 \\ 0 & \omega_{+} \end{bmatrix}, \qquad \tilde{A}_{R} = \begin{bmatrix} \omega_{0} & 0 \\ 0 & \omega_{0} \end{bmatrix}$$

$$\swarrow \quad \forall \text{target state is} \quad \text{reference state is still}$$

factorized Gaussian!

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$$\begin{array}{c} \tilde{A}_{R} = \begin{bmatrix} \omega_{0} & 0 \\ 0 & \omega_{0} \end{bmatrix}$$

$$\begin{array}{c} \text{target state is} \\ \text{factorized Gaussian!} \\ \text{factorized Gaussian!} \\ \end{array}$$

$$\xrightarrow{} \tilde{U}(s) = R U(s) R^{\dagger} = \mathcal{P} \exp \left[\begin{bmatrix} \frac{1}{2} \log \frac{\omega_{-}}{\omega_{0}} & 0\\ 0 & \frac{1}{2} \log \frac{\omega_{+}}{\omega_{0}} \end{bmatrix} s \right]$$

• in normal mode basis, minimal circuit simply scales up diagonal entries

$$egin{aligned} U(s) &= \mathcal{P} \exp\left[rac{1}{2}M_{--} \lograc{\omega_{-}}{\omega_{0}}s + rac{1}{2}M_{++} \lograc{\omega_{+}}{\omega_{0}}s
ight] \ & ext{ with } & M_{\pm\pm} = rac{1}{2}\left(M_{11} + M_{22} \pm M_{12} \pm M_{21}
ight) \end{aligned}$$

• examine lattice of *N* oscillators

$$\longrightarrow A_T = m \, \mathbb{1} \,, \qquad A_R = \omega_0 \, \mathbb{1} \,$$
 "lower bound"

$$\longrightarrow \mathcal{C} = \mathcal{D}_{min} = \frac{1}{2} \sqrt{\sum \log^2 \left(m/\omega_0 \right)} = \frac{N^{1/2}}{2} \log \left(\omega_0/m \right)$$

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$$\text{problem!?!? } \mathcal{C} \sim N^{1/2} = \left[\frac{V}{\delta^{d-1}} \right]^{1/2} \text{ compare } \mathcal{C}_{holo} \sim \frac{V}{\delta^{d-1}}$$

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$$\longrightarrow \text{ action is origin of sq.-root: } \mathcal{D} = \int_0^1 ds \sqrt{\sum_{IJ} \delta_{IJ} Y^I(s) Y^J(s)}$$

 \rightarrow bad action/cost function; need a better choice [discard $F_2 \& F_q$]

• examine lattice of *N* oscillators

• examine lattice of N oscillators \longrightarrow restore $\Omega = 1/\delta$ & $\omega = m$

$$\longrightarrow \mathcal{C} = \mathcal{D}_{min} = \frac{1}{2^{\alpha}} \sum |\log(\omega_{\vec{k}}/\omega_0)|^{\alpha}$$

where for (d - 1)-dimensional (periodic square) lattice:

$$\omega_{\vec{k}}^2 = m^2 + \frac{4}{\delta^2} \sum_i \sin^2 \frac{\pi k_i}{N}, \qquad k_i = 0, 1, \cdots, N^{1/(d-1)} - 1$$

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$$\omega_0 = 1/\ell_0$$
 (IR) with $\ell_0 \gg \delta \longrightarrow C \sim N \log^{\alpha} \left(\frac{\ell_0}{\delta}\right) + \cdots$
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$$\omega_0 = \beta/\delta$$
 (UV) $\longrightarrow C \sim \# \frac{V}{\delta^{d-1}} + \cdots$ \longleftarrow similar to C=A and C=V (α unconstrained)

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QFT:
$$\omega_0$$

• reference state introduces scale

- $\omega_0 \sim 1/R$: complexity is superextensive
- $\omega_0 = \frac{1}{\ell_0}$: complexity depends on new (unphysical) scale

• $\omega_0 \sim 1/\delta$: IR contributions depend on UV cutoff

$$k_{i} = 0, 1, \cdots, N^{1/(d-1)} - 1$$

$$N/2 \longrightarrow \text{crudely, } \omega_{\vec{k}} \sim 1/\delta$$

$$\mathcal{C} \sim N \log^{\alpha} \left(\frac{\ell_{0}}{\delta}\right) + \cdots$$

$$\log\left(\frac{\ell_{0}}{\delta}\right) + \cdots \iff \text{similar to C=A}$$

$$\frac{V}{\delta^{d-1}} + \cdots \iff \text{similar to C=A}$$

$$\operatorname{and C=V}$$

$$(\alpha \text{ unconstrained})$$

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null normals introduce scale

• $\ell \sim V^{1/(d-1)}$: complexity is superextensive

• $\ell = \ell_0$: complexity depends on new (unphysical) scale

• $\ell \sim \delta$: IR contributions depend on UV cutoff, eg, dC_A/dt Dean Carmi, RCM & Pratik Rath

Conclusions/Questions:

- complexity model for free scalar shows surprising similarities to holographic proposals for complexity of boundary CFT states
- possible extensions of QFT model:
 - complexity for excited QFT states? in interacting QFT's?
 - appropriate gate set? appropriate cost functions?
- where is hyperbolic AdS geometry/cMERA in QFT discussion? (See: Chapman, Heller, Marrochio & Pastawski)
- concrete connection to "holographic complexity"?
 - QFT/path integral description of "complexity" in boundary CFT?
 - what is boundary dual of these gravitational observables?
- need/want a better idea?

build $\rho_A \to S_{EE} = -\Sigma \lambda_n \log \lambda_n \longrightarrow$ Replica Trick build optimal $U \to \mathcal{C} = \#$ gates \longrightarrow ?????

preliminary suggestions:
 Caputa, Kundu, Miyaji, Takayanagi & Watanabe (1703.00456; 1706.07056)
 Czech (1706.00965)
 See Takayanagi's talk!

[Talk ends here]

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(Brown, Roberts, Swingle, Stanford, Susskind & Zhao)

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• UV divergences naturally associated with establishing correlations or entanglement down to arbitrarily small length scales

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$$\begin{aligned} \mathcal{C}_{V}(\Sigma) &= \frac{8\pi^{\frac{d+2}{2}}\Gamma(d/2)}{\Gamma(d+2)} C_{T} \int_{\Sigma} d^{d-1}\sigma\sqrt{h} \left[\frac{1}{\delta^{d-1}} -\frac{(d-1)}{2(d-2)(d-3)\delta^{d-3}} \left(\mathcal{R}_{a}^{a} - \frac{1}{2}\mathcal{R} - \frac{(d-2)^{2}}{(d-1)^{2}}K^{2}\right) + \cdots \right] \\ &= f(d) \ C_{T} \ \frac{V_{\Sigma}}{\delta^{d-1}} + \text{ "curvature corrections"} \end{aligned}$$

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$$\begin{split} \mathcal{C}_{V}(\Sigma) &= \frac{1}{\delta^{d-1}} \int_{\Sigma} d^{d-1} \sigma \sqrt{h} \ v_{0}(\mathcal{R}, K) \\ \mathcal{C}_{A}(\Sigma) &= \frac{1}{\delta^{d-1}} \int_{\Sigma} d^{d-1} \sigma \sqrt{h} \left[v_{1}(\mathcal{R}, K) + \log\left(\frac{L}{\alpha \, \delta}\right) \ v_{2}(\mathcal{R}, K) \right] \\ \text{with} \\ v_{k}(\mathcal{R}, K) &= \sum_{n=0}^{\lfloor \frac{d-1}{2} \rfloor} \sum_{i}^{\text{from boundary terms in action}} c_{i,n}^{[k]}(d) \ \delta^{2n} \ [\mathcal{R}, K]_{i}^{2n} \end{split}$$

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